# Note 

# Efficient Integration on the Hypersphere 

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## 1. Introduction

Various applications require the integration of functions on spherical surfaces in Euclidean 4-space. The concept of spherical $t$-designs confers an advantage for the solution of that class of numerical problems. By definition, all points of a $t$-design are equally weighted. Furthermore, suitably chosen spherical designs possess an automorphism group acting transitively on the points. The most interesting group in this context is $I_{4}$, the hypericosahedral group of order 14,400 . It allows the construction of a unique 19 -design containing 3600 integration points furnishing the exact integration of hyperspherical harmonics up to 19 th order, while 20 th order harmonics are integrated with minimized errors.

## 2. The 600-Cell and Its Automorphism Group

Cubature formulas invariant under finite rotation groups have been considered by Sobolev [9], while the special case of the hypericosahedral group was discussed by Salihov [8]. In connection with the theory of spherical designs invented by Delsarte et al. [4], powerful integration formulas can be found. Examples are the 9designs in $\mathbb{R}^{3}$ and 19-designs in $\mathbb{R}^{4}$ given by Goethals et al. [5]. The unique optimal 9 -orbit for any 3-dimensional orthogonal group was constructed by Neutsch [7].

The largest finite orthogonal group in 4-dimensional Euclidean space is the hypericosahedral group $I_{4}$, which can be defined as the automorphism group of the regular 600 -cell (cf. Coxeter [2]). To this end we consider the root system of Coxeter type $H_{4}$ :


It has 120 members. In a suitable coordinate frame $(x, y, z, t)$ these are

$$
\begin{equation*}
(0,0,0,1), \quad \frac{1}{2}(1,1,1,1), \quad \frac{1}{2}\left(1, \lambda, \lambda^{\prime}, 0\right) \tag{2}
\end{equation*}
$$

and all even coordinate permutations and sign reversals, where

$$
\begin{equation*}
\lambda=\frac{1}{2}(-1+\sqrt{5}) \tag{3}
\end{equation*}
$$

and

$$
\begin{equation*}
\lambda^{\prime}=\frac{1}{2}(-1-\sqrt{5}) . \tag{4}
\end{equation*}
$$

They are the 120 vertices of a regular 600 -cell.

## 3. Invariant Polynomials under the Hypericosahedral Group

The degrees of the $I_{4}$-invariant polynomials can be calculated with the help of the Molien series

$$
\begin{equation*}
M\left(I_{4}, \varepsilon\right)=\left|I_{4}\right|^{-1} \sum_{\mu \in I_{4}}|\operatorname{det}(1-\varepsilon \mu)|^{-1} \tag{5}
\end{equation*}
$$

which reduces to

$$
\begin{equation*}
M\left(I_{4}, \varepsilon\right)=\left[\left(1-\varepsilon^{2}\right)\left(1-\varepsilon^{12}\right)\left(1-\varepsilon^{20}\right)\left(1-\varepsilon^{30}\right)\right]^{-1} \tag{6}
\end{equation*}
$$

(Coxeter and Moser [3]). Hence there is a set of four basic invariant polynomials $P_{2}, P_{12}, P_{20}, P_{30}$ of degrees $2,12,20$, and 30 . The natural choice for $P_{2}$ is

$$
\begin{equation*}
P_{2}=x^{2}+y^{2}+z^{2}+t^{2}=\frac{1}{3}\langle 2,0,0,0\rangle . \tag{7}
\end{equation*}
$$

Here the symbol $\langle a, b, c, d\rangle$ denotes

$$
\begin{equation*}
\langle a, b, c, d\rangle=x^{a} y^{b} z^{c} t^{d}+\text { all even permutations of the exponents. } \tag{8}
\end{equation*}
$$

The invariant $P_{12}$ is unique up to a constant factor and the addition of multiples of $P_{2}^{6}$. For convenience we choose $P_{12}$ such that the coefficient of $\langle 12,0,0,0\rangle$ vanishes:

$$
\begin{align*}
P_{12}= & 2\langle 10,2,0,0\rangle-6\langle 8,4,0,0\rangle-12\langle 8,2,2,0\rangle \\
& +7\langle 6,6,0,0\rangle+(9-33 \sqrt{5})\langle 6,4,2,0\rangle+(9+33 \sqrt{5})\langle 6,4,0,2\rangle  \tag{9}\\
& +10\langle 4,4,4,0\rangle+116\langle 6,2,2,2\rangle-135\langle 4,4,2,2\rangle
\end{align*}
$$

and

$$
\begin{align*}
& P_{20}=\Delta \Delta\left(P_{12}^{2}\right),  \tag{10}\\
& P_{30}=\Delta\left(P_{12} P_{20}\right), \tag{11}
\end{align*}
$$

where $\Delta$ is the Laplacian in Euclidean 4-space

$$
\begin{equation*}
\Delta=\partial_{x}^{2}+\partial_{y}^{2}+\partial_{z}^{2}+\partial_{t}^{2} \tag{12}
\end{equation*}
$$

As usual, the average of a function $P$ over the hypersphere

$$
\begin{equation*}
\Omega_{4}=\left\{(x, y, z, t) \in \mathbb{R}^{4} \mid x^{2}+y^{2}+z^{2}+t^{2}=1\right\} \tag{13}
\end{equation*}
$$

is defined by

$$
\begin{equation*}
M_{4}(P)=\frac{1}{\operatorname{Vol} \Omega_{4}} \int_{\Omega_{4}} P d \Omega_{4} . \tag{14}
\end{equation*}
$$

Hence

$$
\begin{equation*}
M_{4}(\langle a, b, c, d\rangle)=12 \cdot 2^{-2(a+b+c+d)} \cdot \frac{(2 a)!(2 b)!(2 c)!(2 d)!}{a!b!c!d!(a+b+c+d+1)!} \tag{15}
\end{equation*}
$$

and thus

$$
\begin{align*}
M_{4}\left(P_{2}\right) & =1,  \tag{16}\\
M_{4}\left(P_{12}\right) & =1 / 14,  \tag{17}\\
M_{4}\left(P_{20}\right) & =12672 / 7,  \tag{18}\\
M_{4}\left(P_{30}\right) & =13542912 / 91 . \tag{19}
\end{align*}
$$

These results were obtained through the use of the REDUCE 3 algebraic manipulation system (Hearn [6]).

We recall the following definitions: A finite set $N$ of unit vectors in Euclidean 4space is called a spherical $t$-design if for all polynomials $P$ of degree $\leqslant t$ the $N$ average of $P$ equals $M_{4}(P)$ (Delsarte, Goethals, and Seidel [4]). Furthermore, if $N$ is transitively permuted by a finite orthogonal group $G$, we say that $N$ is a $t$-orbit of $G$ (Neutsch [7]).

We are now able to formulate the following
Theorem. Every orbit of the hypericosahedral group $I_{4}$ which is contained in the surface of the unit hypersphere is an 11-design. There are infinitely many 19-orbits of $I_{4}$, but no 20 -orbits. Exactly one of these 19 -orbits is optimal with respect to integration of polynomials of degree 20.

The 3600 integration points are of the form $C_{1} E_{1}+C_{2} E_{2}$, where $E_{1}$ and $E_{2}$ are vertices of the 600 -cell which are mutually orthogonal, while the coefficients $C_{1}$ and $C_{2}$ are approximately:

$$
\begin{array}{lllll}
C_{1}=0.97129 & 92948 & 30434 & 51205 & 35832, \\
C_{2}=0.23786 & 06311 & 72753 & 45523 & 39919 .
\end{array}
$$

Proof. In analogy to the 3-dimensional case (Neutsch [7]), the first two assertions are obvious because $P_{12}$ and $P_{20}$ are the smallest degree nonconstant $I_{4}$ invariant polynomials. The point $(x, y, z, t)$ generates a 19 -orbit of the group if

$$
\begin{equation*}
P_{2}(x, y, z, l)=M_{4}\left(P_{2}\right)=1 \tag{20}
\end{equation*}
$$

and

$$
\begin{equation*}
P_{12}(x, y, z, t)=M_{4}\left(P_{12}\right)=\frac{1}{14} . \tag{21}
\end{equation*}
$$

The point $(x, y, z, t)$ compatible with $(20,21)$ yields an extremum of $P_{20}$ if for all vectors $v$ tangent to the intersection of (20) and (21)

$$
\begin{equation*}
\mathbf{v} \nabla P_{20}=0 \tag{22}
\end{equation*}
$$

holds, where $\nabla$ denotes the gradient. This means that $\nabla P_{2}, \nabla P_{12}, V P_{20}$ are linearly dependent. Hence $\nabla P_{2}, \nabla P_{12}, \nabla P_{20}, \nabla P_{30}$ are also linearly dependent:

$$
\begin{equation*}
\operatorname{det}\left(\nabla P_{2}, \nabla P_{12}, \nabla P_{20}, \nabla P_{30}\right)=0 \tag{23}
\end{equation*}
$$

The reflection $t \rightarrow-t$ is an element of $I_{4}$; thus all invariants of $I_{4}$ are even functions of $t$. If we set $t=0$, the fourth line of the determinant (23) vanishes. The hyperplane $t=0$ is therefore a solution of (23), and similarly, all its images under $I_{4}$. The union of these 60 hyperplanes forms the complete solution of (23) as the determinant is a homogeneous polynomial of degree 60 . Without loss of generality, we may set $t=0$ and use

$$
\begin{equation*}
P^{*}(x, y, z)=P(x, y, z, 0) \tag{24}
\end{equation*}
$$

Equations (20)-(22) reduce to

$$
\begin{array}{r}
P_{2}^{*}(x, y, z)=1, \\
P_{12}^{*}(x, y, z)=\frac{1}{14}, \\
\operatorname{det}\left(\nabla P_{2}^{*}, \nabla P_{12}^{*}, \nabla P_{20}^{*}\right)=0 . \tag{27}
\end{array}
$$

The subgroup of $I_{4}$ fixing $(0,0,0,1)$ is isomorphic to the icosahedral group $I_{3}$. We use as the basic invariants of $I_{3}$ :

$$
\begin{align*}
Q_{2}= & x^{2}+y^{2}+z^{2}  \tag{28}\\
Q_{6}= & 4 x^{2} y^{2} z^{2}+\lambda\left(x^{4} y^{2}+y^{4} z^{2}+z^{4} x^{2}\right)+\lambda^{\prime}\left(x^{2} y^{4}+y^{2} z^{4}+z^{2} x^{4}\right)  \tag{29}\\
Q_{10}= & \sqrt{5}\left(x^{4}+y^{4}+z^{4}-2 x^{2} y^{2}-2 y^{2} z^{2}-2 z^{2} x^{2}\left(\left(\lambda^{\prime 6}-\lambda^{6}\right) x^{2} y^{2} z^{2}\right.\right. \\
& \left.+\lambda^{2}\left(x^{2} y^{4}+y^{2} z^{4}+z^{2} x^{4}\right)-\lambda^{\prime 2}\left(x^{4} y^{2}+y^{4} z^{2}+z^{4} x^{2}\right)\right) \tag{30}
\end{align*}
$$

as defined in Neutsch [7, Eqs. (13)-(15)]. $P_{2}^{*}, P_{12}^{*}$, and $P_{20}^{*}$ are invariant under $I_{3}$ and can be expressed in terms of $Q_{2}, Q_{6}, Q_{10}$ :

$$
\begin{align*}
P_{2}^{*}= & Q_{2},  \tag{31}\\
P_{12}^{*}= & -\frac{3}{2} Q_{2}^{3} Q_{6}-6 Q_{6}^{2}-\frac{1}{2} Q_{2} Q_{10},  \tag{32}\\
P_{20}^{*}= & 480 Q_{2}^{10}-26880 Q_{2}^{7} Q_{6}-90096 Q_{2}^{4} Q_{6}^{2}-92928 Q_{2} Q_{6}^{3}-8960 Q_{2}^{5} Q_{10} \\
& +11616 Q_{2}^{2} Q_{6} Q_{10}+1936 Q_{10}^{2} . \tag{33}
\end{align*}
$$

Hence (27) can be rewritten as

$$
\begin{align*}
& \operatorname{det}\left(\nabla Q_{2}, \nabla Q_{6}, \nabla Q_{10}\right) \operatorname{det} \frac{\partial\left(P_{2}^{*}, P_{12}^{*}, P_{20}^{*}\right)}{\partial\left(Q_{2}, Q_{6}, Q_{10}\right)} \\
& \quad=-46464 Q_{6} Q_{10} \operatorname{det}\left(\nabla Q_{2}, \nabla Q_{6}, \nabla Q_{10}\right)=0 . \tag{34}
\end{align*}
$$

There are three cases to be distinguished:

$$
\begin{array}{ll}
\text { case 1: } & \operatorname{det}\left(\nabla Q_{2}, \nabla Q_{6}, \nabla Q_{10}\right)=0, \\
\text { case 2: } & Q_{10}(x, y, z)=0, \\
\text { case 3: } & Q_{6}(x, y, z)=0 . \tag{37}
\end{array}
$$

The icosahedral group $I_{3}$ transitively permutes the 12 vertices, 20 faces, and 30 edges of a regular icosahedron inscribed into the unit sphere.

Case 1. We use the same procedure as with $I_{4}$ above (Eq. (23)), and find the complete solution to be the union of the 15 planes normal to the icosahedron's 15 pairs of edge-centres. For reasons of transitivity we may restrict ourselves to one of these planes, e.g., $z=0$. Condition (25) reduces to

$$
\begin{equation*}
P_{2}^{*}(x, y, 0)=Q_{2}(x, y, 0)=x^{2}+y^{2}=1 . \tag{38}
\end{equation*}
$$

We substitute

$$
\begin{equation*}
2 x^{2}=1+\mu 5^{-1 / 2} ; 2 y^{2}=1-\mu 5^{-1 / 2} \tag{39}
\end{equation*}
$$

and obtain

$$
\begin{gather*}
Q_{6}(x, y, 0)=-\frac{1}{40}(\mu-1)\left(\mu^{2}-5\right)  \tag{40}\\
Q_{10}(x, y, 0)=\frac{1}{200}(3 \mu+5) \mu^{2}\left(\mu^{2}-5\right) \tag{41}
\end{gather*}
$$

Using (32) we derive

$$
\begin{equation*}
21 \mu^{6}-119 \mu^{4}+175 \mu^{2}-125=0 \tag{42}
\end{equation*}
$$

The only real solution for $\mu^{2}$ is

$$
\begin{equation*}
\mu^{2}=\frac{1}{9}\left(17+\frac{2}{\sqrt[3]{7}}[\sqrt[3]{1177+135 \sqrt{65}}+\sqrt[3]{1177-135 \sqrt{65}}]\right) \tag{43}
\end{equation*}
$$

or

$$
\begin{equation*}
\mu= \pm 1.9830449011 \tag{44}
\end{equation*}
$$

and

$$
\begin{equation*}
x= \pm 0.9712992948 ; \quad y= \pm 0.2378606312 \tag{45}
\end{equation*}
$$

for positive $\mu$. The values of $x$ and $y$ are interchanged for the negative solution. Hence

$$
\begin{align*}
& P_{20}^{*}(x, y, 0)=\frac{44}{39,375}\left(2123 \mu^{4}-3875 \mu^{2}+1,598,375\right)  \tag{46}\\
& P_{20}^{*}(x, y, 0)=1805.889296<M_{4}\left(P_{20}\right) \tag{47}
\end{align*}
$$

Case 2. Case 2 has no real solutions.

## Case 3. Using

$$
\begin{equation*}
Q_{6}(x, y, z)=0 \tag{48}
\end{equation*}
$$

and (26) and (32) we find

$$
\begin{equation*}
Q_{10}(x, y, z)=-\frac{1}{7} . \tag{49}
\end{equation*}
$$

Thus

$$
\begin{equation*}
P_{20}^{*}(x, y, z)=\frac{88,176}{49}=1799.510204<M_{4}\left(P_{20}\right) \tag{50}
\end{equation*}
$$

by virtue of (33). Both cases (1 and 3) yield values of $P_{20}$ smaller than $M_{4}\left(P_{20}\right)$; hence there is no 20 -orbit of $I_{4}$. The optimal 19 -orbit is given by case 1 . The length of that orbit is 3600 . Points are generated by application of $I_{4}$ to any one of them, e.g.,

$$
\begin{equation*}
(x, y, z, t)=(\sqrt{(1+\delta) / 2}, \sqrt{(1-\delta) / 2}, 0,0) \tag{51}
\end{equation*}
$$

with

$$
\begin{equation*}
\delta^{2}=\frac{1}{45}\left[17+\frac{2}{\sqrt[3]{7}}(\sqrt[3]{1177+135 \sqrt{65}}+\sqrt[3]{1177-135 \sqrt{65}})\right] \tag{52}
\end{equation*}
$$

Numerical values with an accuracy of 25 digits are

$$
\begin{align*}
& x=0.9712992948304345120535832,  \tag{53}\\
& y=0.2378606311727534552339919 . \tag{54}
\end{align*}
$$

This completes the proof of the theorem.

## 4. Conclusions

We have demonstrated the existence of a unique optimal 19-orbit of the group $I_{4}$ containing 3600 points. These equally weighted points are generated by simple operations like reflections in the roots of the Coxeter system $H_{4}$. They are all the vectors of the form $C_{1} E_{1}+C_{2} E_{2}$, where ( $E_{1}, E_{2}$ ) represent the $120 \times 30$ ordered pairs of vertices of the 600 -cell (given by Eq. (2)) which are orthogonal to each other. Obviously, simply generated and equally weighted points confer an advantage in integration procedures.

## Appendix

We list the vertices and centres of the edges, faces, and cells of the $600-\mathrm{celll}$. For each vector given there are additional ones (not listed here) that are formed by even permutations of the coordinates and/or sign reversals. Their number is given in each case. The definition of the following quantities is helpful:

$$
\begin{align*}
\lambda & =\left(-1+5^{1 / 2}\right) / 2  \tag{A1}\\
\lambda^{\prime} & =\left(-1-5^{1 / 2}\right) / 2  \tag{A2}\\
s & =\left(\left(5+5^{1 / 2}\right) / 2\right)^{1 / 2}  \tag{A3}\\
s^{\prime} & =\left(\left(5-5^{1 / 2}\right) / 2\right)^{1 / 2} \tag{A4}
\end{align*}
$$

The 120 vertices are

$$
\begin{array}{ll}
(0,0,0,1) & \#=8 \\
\frac{1}{2}(1,1,1,1) & \#=16 \\
\frac{1}{2}\left(1, \lambda, \lambda^{\prime}, 0\right) & \#=96
\end{array}
$$

The 720 edge centres are

$$
\begin{array}{ll}
5^{-1 / 2}\left(0,0, s, s^{\prime}\right) & \#=48 \\
20^{-1 / 2}\left(s+s^{\prime}, s+s^{\prime}, s-s^{\prime}, s-s^{\prime}\right) & \#=96 \\
20^{-1 / 2}\left(0, s, s+s^{\prime}, 2 s-s^{\prime}\right) & \#=96 \\
20^{-1 / 2}\left(0, s^{\prime}, s+2 s^{\prime}, s-s^{\prime}\right) & \#=96 \\
20^{-1 / 2}\left(s, 2 s, s^{\prime}, s-s^{\prime}\right) & \#=192 \\
20^{-1 / 2}\left(s, 2 s^{\prime}, s^{\prime}, s+s^{\prime}\right) & \#=192 \tag{A13}
\end{array}
$$

The 1200 face centres are

$$
\begin{array}{ll}
3^{-1 / 2}(0,1,1,1) & \#=32 \\
3^{-1 / 2}\left(0,0, \lambda, \lambda^{\prime}\right) & \#=48 \\
12^{-1 / 2}(1,1,1,3) & \#=64 \\
12^{-1 / 2}\left(0, \lambda, 3, \lambda^{\prime}\right) & \#=96 \\
12^{-1 / 2}\left(0, \lambda^{2}, \lambda^{2}, \lambda-\lambda^{\prime}\right) & \#=96 \\
12^{-1 / 2}\left(1,1, \lambda-\lambda^{\prime}, \lambda-\lambda^{\prime}\right) & \#=96 \\
12^{-1 / 2}\left(1,2 \lambda^{\prime}, \lambda, \lambda^{2}\right) & \#=192 \\
12^{-1 / 2}\left(1, \lambda^{\prime 2}, \lambda^{\prime}, 2 \lambda\right) & \#=192 \\
12^{-1 / 2}\left(1,2, \lambda^{\prime 2}, \lambda^{2}\right) & \#=192 \\
12^{-1 / 2}\left(\lambda, 2, \lambda^{\prime}, \lambda-\lambda^{\prime}\right) & \#=192 \tag{A23}
\end{array}
$$

The 600 cell centres are

$$
\begin{array}{ll}
2^{-1 / 2}(0,0,1,1) & \#=24 \\
8^{-1 / 2}\left(1,1,1, \lambda-\lambda^{\prime}\right) & \#=64 \\
8^{-1 / 2}\left(\lambda, \lambda, \lambda, \lambda^{\prime 2}\right) & \#=64 \\
8^{-1 / 2}\left(\lambda^{\prime}, \lambda^{\prime}, \lambda^{\prime}, \lambda^{2}\right) & \#=64 \\
8^{-1 / 2}\left(0,1, \lambda^{2}, \lambda^{\prime 2}\right) & \#=96 \\
8^{-1 / 2}\left(0, \lambda^{\prime}, \lambda, \lambda-\lambda^{\prime}\right) & \#=96 \\
8^{-1 / 2}\left(1,2, \lambda, \lambda^{\prime}\right) & \#=192 \tag{A30}
\end{array}
$$

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